The Science of Software and System Design

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Science = knowledge that helps us make predictions

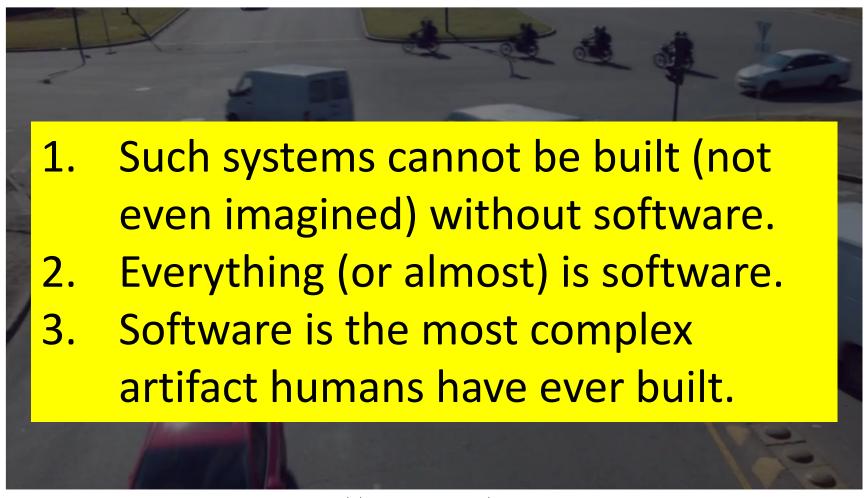
- Science of software: what predictions can we make about the programs we write?
 - My program terminates
 - My program doesn't throw an exception
 - My program satisfies properties X, Y, Z, ...
- Science of systems (safety-critical, real-time, embedded, cyber-physical, secure, ... systems)
 - Many specialized techniques (e.g., for linear systems, ...)
 - Thesis: same fundamental methods as for software

Cyber-physical systems: present



Autonomous car driving through red light

'Cyber-physical' systems: future



Software and complexity

```
int x := input an integer number > 1;
while x > 1 {
  if x is even
      x := x / 2;
  else
      x := 3*x + 1;
}
```

Run starting at 31: 31 94 47 142 71 214 107 322 161 484 242 121 364 182 91 274 137 412 206 103 310 155 466 233 700 350 175 526 263 790 395 1186 593 1780 890 445 1336 668 334 167 502 251 754 377 1132 566 283 850 425 1276 638 319 958 479 1438 719 2158 1079 3238 1619 4858 2429 7288 3644 1822 911 2734 1367 4102 2051 6154 3077 9232 4616 2308 1154 577 1732 866 433 1300 650 325 976 488 244 122 61 184 92 46 23 70 35 106 53 160 80 40 20 10 5 16 8 4 2

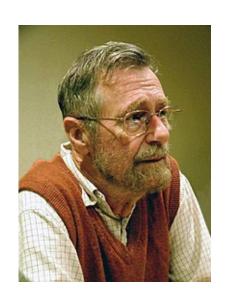
Collatz conjecture:

the program terminates for every input.

Open problem in mathematics.

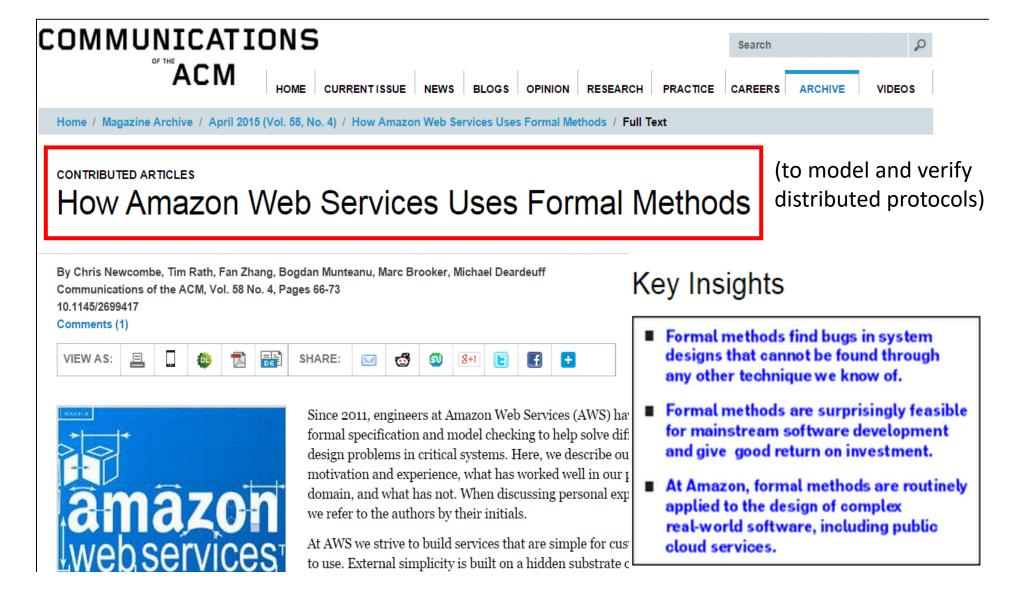
Basic software and system design methods

- Testing (trial and error)
- Proving (specification/verificationbased design, model-based design)



"Testing can be used to show the presence of bugs, but never to show their absence!" [Dijkstra, 1970]

Formal verification: a successful and practical approach



Boeing 737 Max 8 accidents

- 2 accidents within 5 months 346 deaths
- 737 Max 8 planes grounded world-wide since March 2019
- Control system rather than pilot errors
- Dubious business and certification practices





Recent work topics

The Refinement Calculus of Reactive Systems

 Synthesis of distributed protocols – with connections to learning

 Synthesis of platform mappings – with applications to security

Multi-view modeling

The Refinement Calculus of Reactive Systems (RCRS)

Joint work with Viorel Preoteasa and Iulia Dragomir (Aalto)
Sponsors: Academy of Finland and NSF CPS Breakthrough

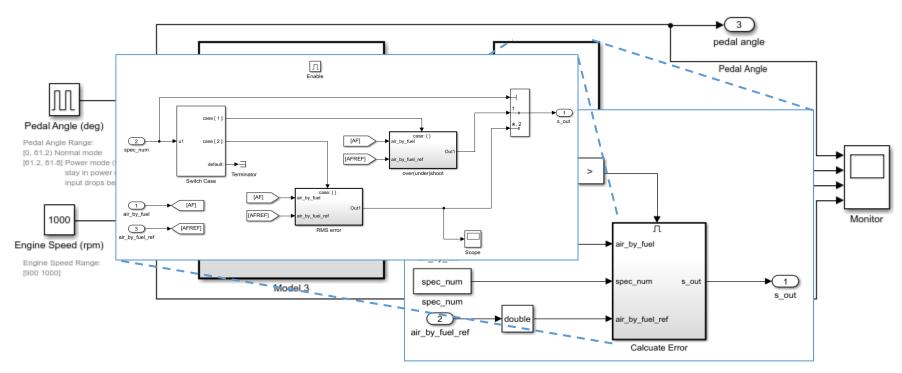






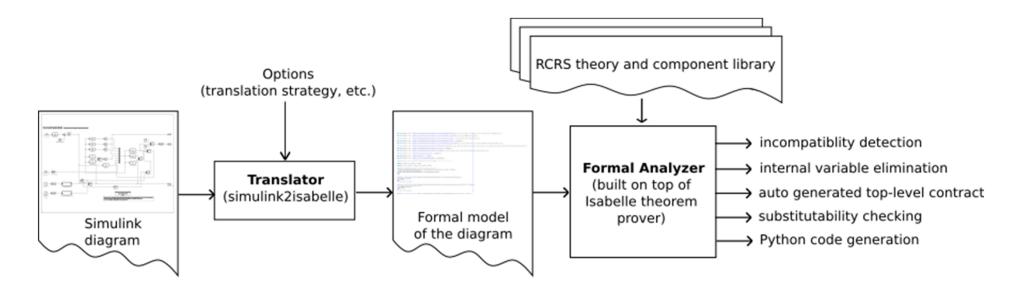
Modeling cyber-physical systems compositionally

Simulink: a de-facto standard



Distinguished Artifact Award TACAS 2018

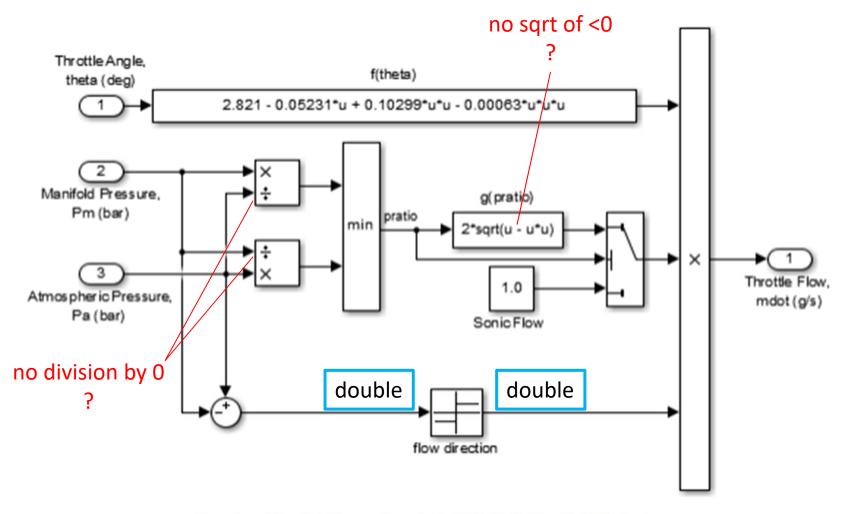
RCRS: theory & tool for compositional formal analysis of Simulink models



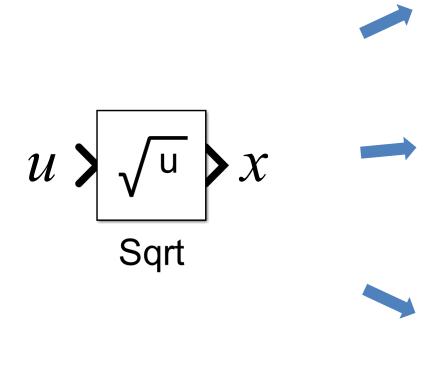
RCRS theory: contract-based design

- Relational interfaces [EMSOFT'09, ACM TOPLAS'11]
 - Symbolic, synchronous version of interface automata [Alfaro, Henzinger]
 - Open, non-deterministic, non-input-complete systems (this is crucial for static analysis)
 - Semantic foundation: relations
 - Limited to safety properties
- Refinement calculus of reactive systems [EMSOFT'14]
 - Richer semantics: predicate and property transformers
 - Can handle both safety and liveness properties
 - Entirely formalized in Isabelle theorem prover 30k lines of Isabelle code

Static ('compile-time') analysis



Simulink square root modeled with RCRS contracts



double -> double

Simulink type

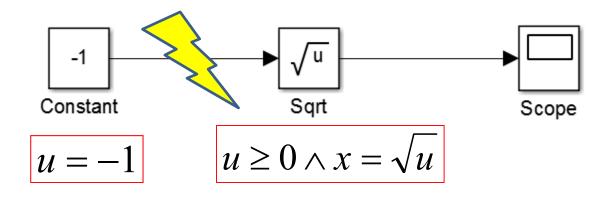
$$u \ge 0 \longrightarrow x = \sqrt{u}$$

RCRS contract: input-receptive

$$u \ge 0 \land x = \sqrt{u}$$

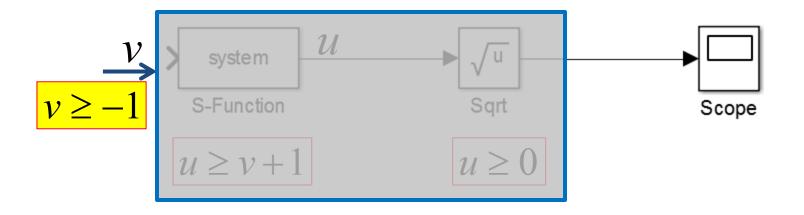
RCRS contract: non-input-receptive

Catching incompatibilities statically

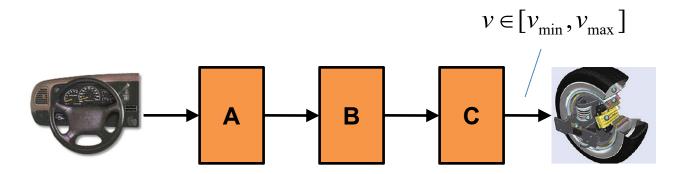


caught by taking the conjunction of the two formulas and checking satisfiability

Inferring new contracts automatically

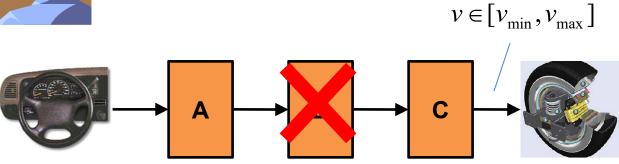


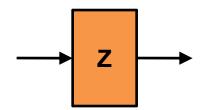
Suppose we have designed and verified this "steer-by-wire" system:





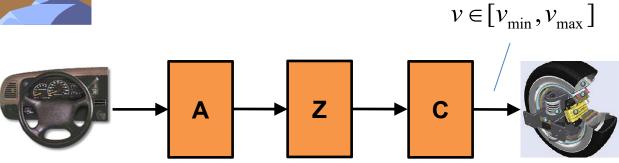
Suppose we want to replace B with Z:





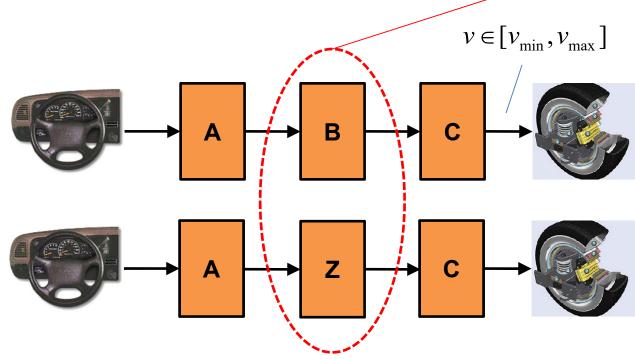


How to ensure properties are preserved (substitutability)?



Compositional theories like RCRS offer **local** verification methods.

Z ≤ B: Z refines B (local check)

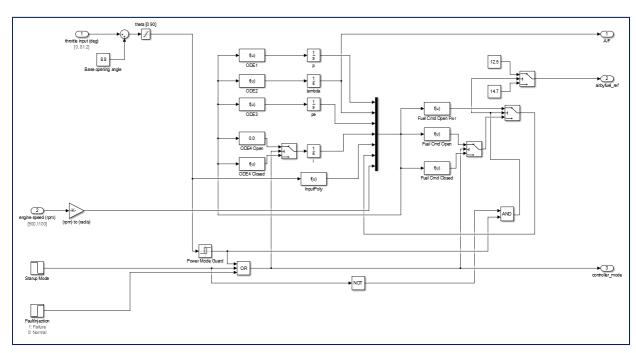


Does it work for real-world systems?

- Case study: Fuel Control System automotive benchmark
- Made publicly available by Toyota on CPS-VO website
- Simulink model: 3-level hierarchy, 104 blocks
- Translator produces a 1660-line long RCRS theory (translation time negligible)
- Automatic static analysis / contract inference / simplification:

<1 minute

Sample subsystem of the FCS model



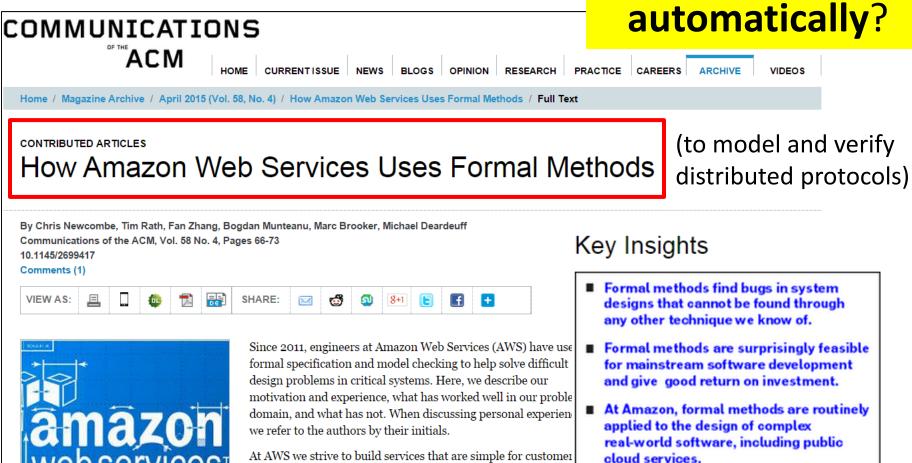
Automatic synthesis of distributed protocols

Joint work with Rajeev Alur, Christos Stergiou et al (UPenn)
Sponsors: NSF Expeditions ExCAPE

Motivation: distributed protocols

Notoriously hard to get right

Can we synthesize such protocols automatically?



to use. External simplicity is built on a hidden substrate of

Verification and synthesis in a nutshell

Verification:

- 1. Design system "by hand": S
- 2. State system requirements: ϕ
- 3. Check: does S satisfy ϕ ?
- Synthesis (ideally):
 - 1. State system requirements: ϕ
 - 2. Generate automatically system S that satisfies ϕ by construction.

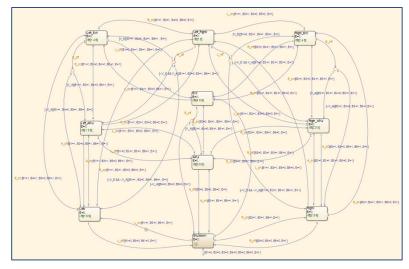
State of the art synthesis

From formal specs to discrete controllers:

```
#Assumptions
(gl_healthy & gr_healthy & al_healthy & ar_healthy)
[](gl_healthy | gr_healthy | al_healthy | ar_healthy)
[](gl_healthy -> X(!gl_healthy) )
[](!gr_healthy -> X(!gr_healthy) )
[](!al_healthy -> X(!al_healthy) )
[](!ar_healthy -> X(!ar_healthy) )

#Guarantees
(!cl & !c2 & !c3 & !c4 & !c5 & !c6 & !c7 & !c8 & !c9 & !c10 & !c11 & !c12 & !c13)
[](X(c7) & X(c8) & X(c11) & X(c12) & X(c13))
[](!(c2 & c3))
[](!(c1 & c5 & (al_healthy | ar_healthy)))
[](!(c4 & c6 & (al_healthy | ar_healthy)))
[](!(x(gl_healthy) & X(gr_healthy) ) -> X(!c2) & X(!c3) & X(!c9) & X(!c10))
[]((X(!gl_healthy) & X(!gr_healthy) ) -> X(c9) & X(c10))
...
```





Specification (temporal logic formulas)

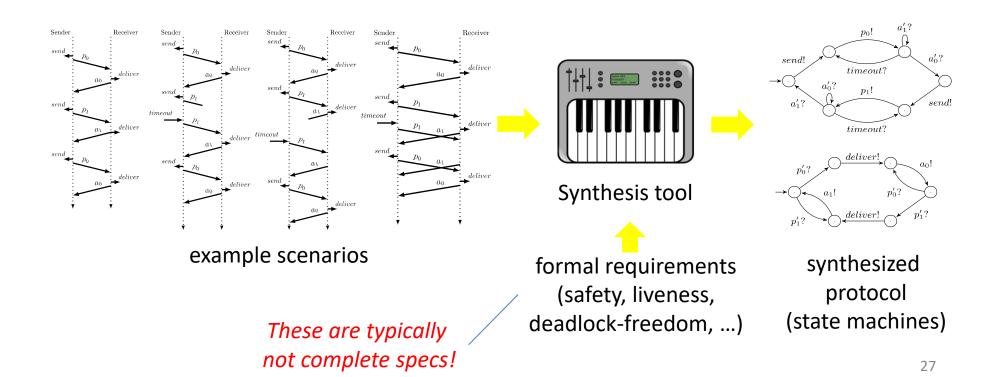
Controller (state machine)

Limitations:

- Scalability (writing full specs & synthesizing from them)
- Not applicable to distributed protocols (undecidable)

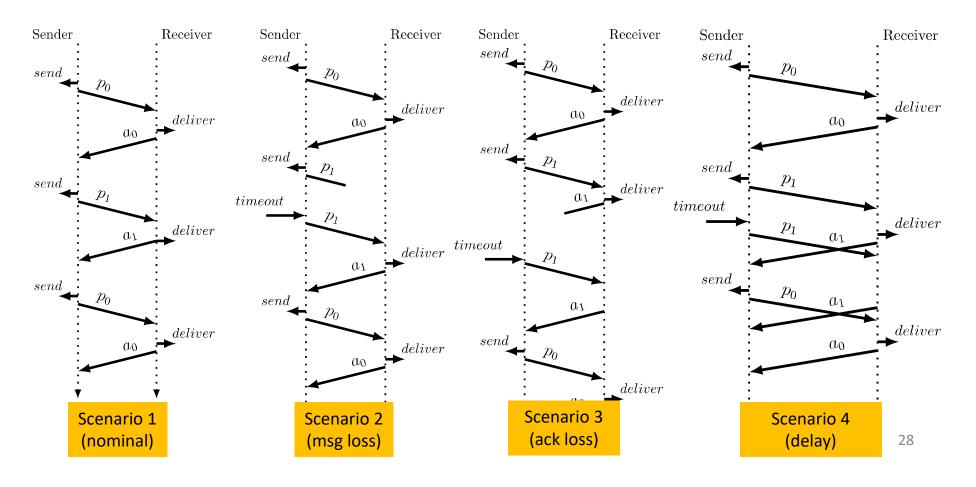
Synthesis of Distributed Protocols from Scenarios and Requirements

• Idea: combine requirements + example scenarios



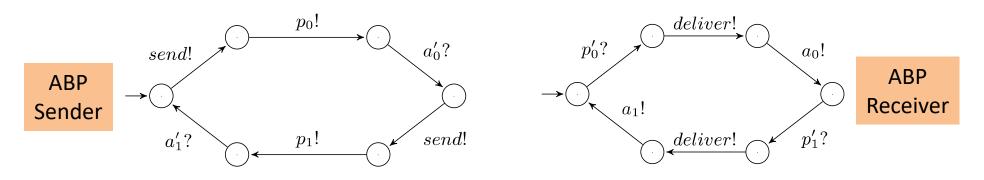
Scenarios: message sequence charts

- Describe what the protocol must do in some cases
- Intuitive language ⇒ good for the designer
- Only a few scenarios required (1-10)

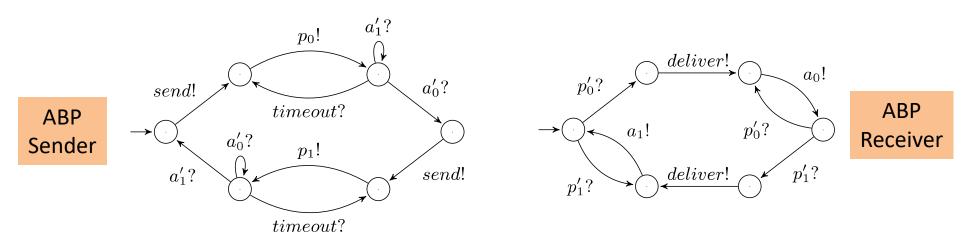


Synthesis becomes a completion problem

Incomplete automata learned from first scenario:

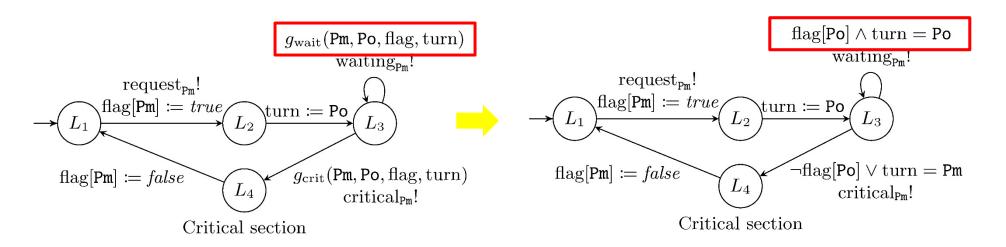


Automatically completed automata:



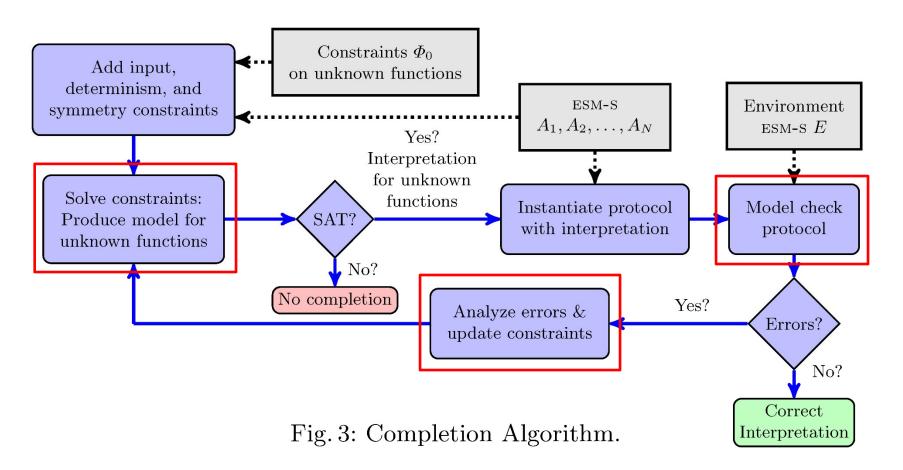
Results

- Able to synthesize the distributed Alternating Bit Protocol (ABP) and other simple finite-state protocols (cache coherence, consensus, ...) fully automatically [HVC'14, ACM SIGACT'17].
- Towards industrial-level protocols described as extended state machines [CAV'15].



Algorithmic technique: counter-example guided completion of (extended) state machines

 Completion of incomplete machines: find missing transitions, guards, assignments, etc.



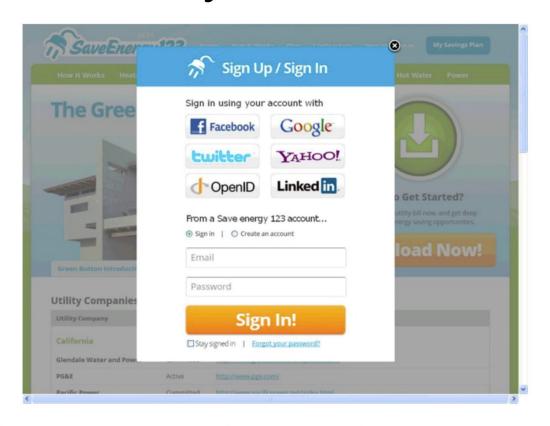
Synthesis of platform mappings with applications to security

Joint work with Eunsuk Kang (NSF ExCAPE project), and Stephane Lafortune (UMichigan) Sponsors: NSF SaTC program

Thanks to Eunsuk Kang for several slides

Motivation: security

Third-Party Authentication



OAuth: Widely adapted, support from major vendors Well-scrutinized & **formally checked**

Motivation: security



by Chris Brook May 2, 2014, 1:42 pm

UPDATE — A serious vulnerability in the OAuth and OpenID protocols could lead to complications for those who use the services to log in to websites like Facebook, Google, LinkedIn, Yahoo, and Microsoft among many others.

Study of OAuth providers [Sun & Beznosov, CCS12] Majority vulnerable (Google, Facebook,...)

The heart of the problem

Application Design Deployment

Platform

Designers think at high-level

Protocols, APIs, workflows, use cases, etc., Ignore irrelevant details

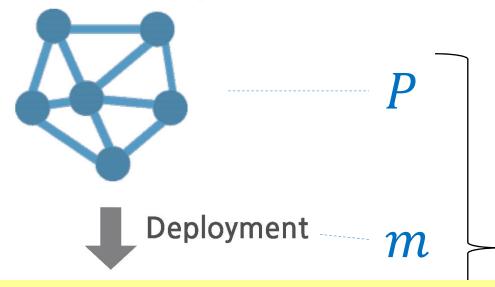
implementation

Attacks may exploit details absent at high-level

Unwanted features
Unknown environment
Hidden interface/entry points

Our approach: modular modeling with mappings

Application Design



mapping composition operator



Examples of decisions captured by mappings:

- should a certain protocol message be implemented as an HTTP request?
- with cookies to store secret values?
- with query parameters?

Possible applications beyond security.





Verification and synthesis problems on mappings

• Verification: given application model P, platform model Q, mapping m, and some specification ϕ , check that the system $P \mid \mid_m Q$ satisfies ϕ .

• Synthesis: given P, Q and ϕ , find mapping m, such that $P \mid_{m} Q$ satisfies ϕ .

Contributions [CAV 2019]

- Algorithm and tool for automated mapping synthesis:
 - Counter-example guided symbolic search over possible candidate mappings
- Real-world case studies: OAuth 2.0 and 1.0
 - Tool able to automatically synthesize correct mappings for both OAuth 2.0 and 1.0
 - Synthesized mappings describe mitigations to wellknown attacks (e.g., session swapping, covert redirect, session fixation)
 - Several 1000s LOC of application and platform models:
 OAuth, HTTP server, HTTP browser, ...

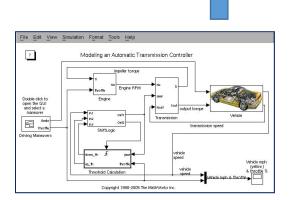
Multi-view modeling

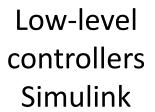
Joint work with Jan Reineke (Saarland), Christos Stergiou (now at Google), and Maria Pittou (ex PhD student)

Part of NSF Project COSMOI

Multi-View Modeling

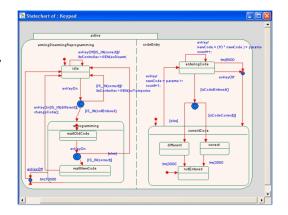
Complex system -> many stakeholders -> many design teams -> many viewpoints -> many perspectives -> many models = views

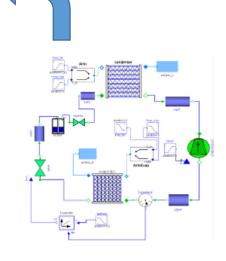






Supervisory controllers Rhapsody/ SysML



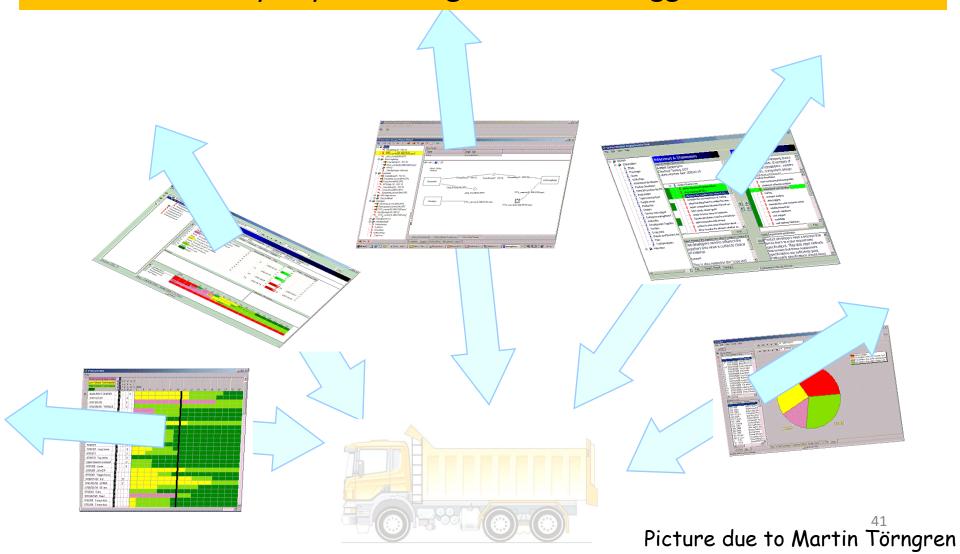


Physical dynamics Modelica

Problem: View Consistency

Partially overlapping content -> potential for contradictions

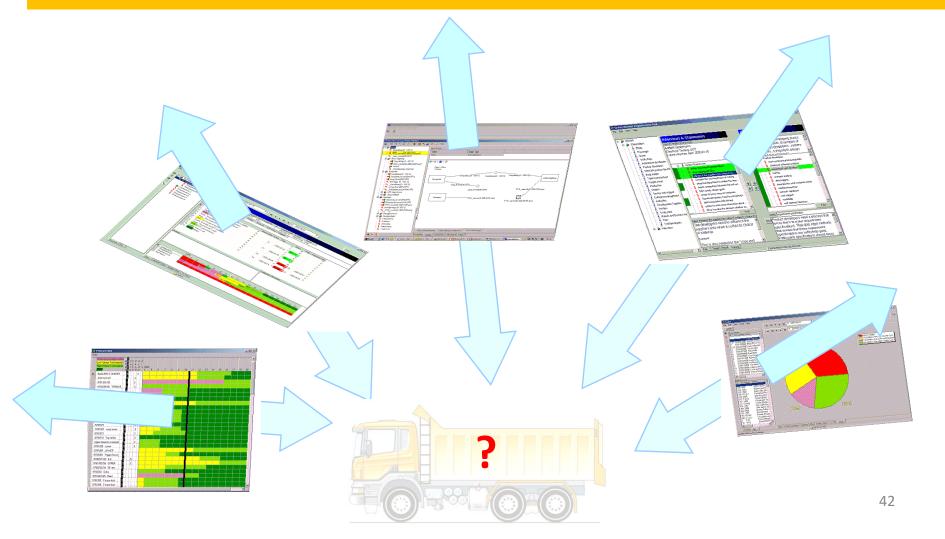
Industry: "system integration is the biggest issue"



What is view consistency, formally?

A set of views are consistent =

3 witness system that could generate those views

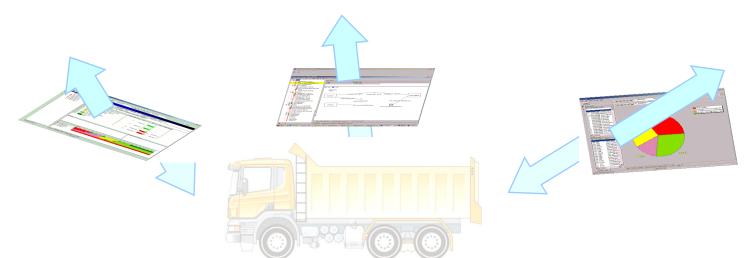


From (separate) components to (overlapping) views

- Refinement theories
 - model interacting but separate components



- Multi-view modeling
 - Views model overlapping aspects



[TACAS'14, SAMOS'16, FACS'16, SoSyM'18]

Contributions

- An abstract formal framework for reasoning about multi-view modeling
 - Systems and views are sets of behaviors, but generally in different domains.
 - Abstraction functions map system behaviors to view behaviors.
 - View consistency, synthesis, etc problems defined in this framework.
- Instantiation of the framework for various types of discrete systems and different types of abstraction functions:
 - Symbolic transition systems, finite regular and Buchi automata (regular and omega-regular languages).
 - Projections, periodic sampling, ...
- Study decidability and complexity of checking consistency and synthesizing a witness system.

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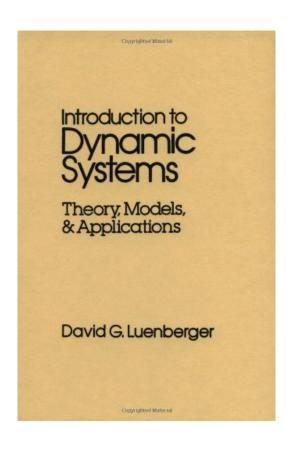
SOME THOUGHTS ON EDUCATION

What is the mathematics of the science of software?

Logic



Systems theory (classic)



1979

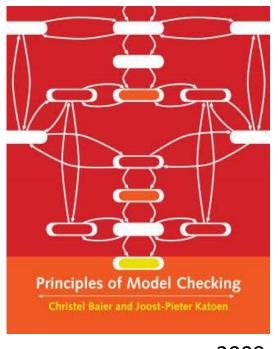
ALAN V. OPPENHEIM
ALAN S. WILLSKY
WITH S. HAMID NAWAB

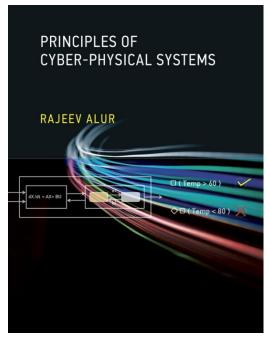
Second Edition

Study specific classes of systems (e.g., linear/non-linear differential equations)

1983

Systems theory (modern)





and many, many others ...

2008

2015

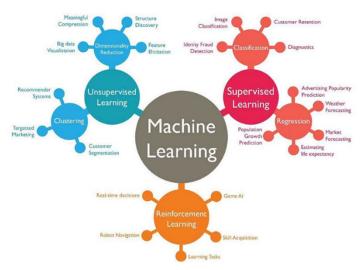
Study general and fundamental concepts to all systems (e.g., states, transitions, reachability, safety, liveness, fairness, correctness, refinement, compositionality, ...)

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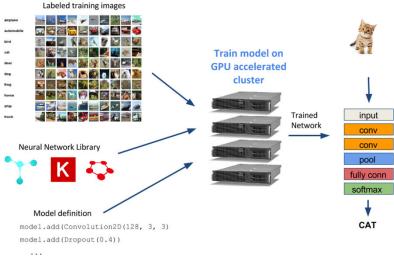
PERSPECTIVES

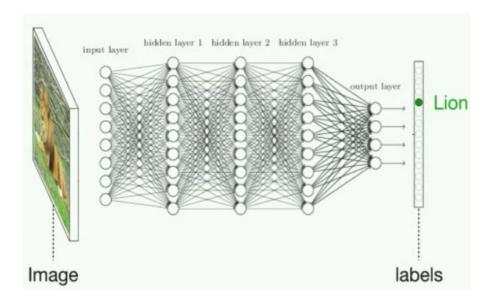
Brave new world











Tripakis

New challenges and opportunities

 Can AI benefit from the science of software, and how?

 Can the science of software benefit from AI, and how?

Can AI benefit from the science of software?

- Yes.
- Al software is untestable.
- Formal verification of Al software is needed.



Driving to Safety

How Many Miles of Driving Would It Take to Demonstrate Autonomous Vehicle Reliability?

Nidhi Kalra, Susan M. Paddock

Key findings

- Autonomous vehicles would have to be driven hundreds of millions of miles and sometimes hundreds of billions of miles to demonstrate their reliability in terms of fatalities and injuries.
- Under even aggressive testing assumptions, existing fleets would take tens and sometimes hundreds of years

n the United States, roughly 32,000 people are killed and more than two million injured in crashes every year (Bureau of Transportation Statistics, 2015). U.S. motor vehicle crashes as a whole can pose economic and social costs of more than \$800 billion in a single year (Blincoe et al., 2015). And, more than 90 percent of crashes are caused by human errors (National Highway Traffic Safety Administration, 2015)—such as driving too fast and misjudging other drivers' behaviors, as well as alcohol impairment, distraction, and fatigue.

Can the science of software benefit from AI?

- Yes.
- Model learning (and its connections to machine learning).
- Data-driven and Model-based Design (DMD)
 - Top-down: from specification to implementation (specialization)
 - Bottom-up: learning from examples (generalization)

An example of DMD: combining synthesis with learning

- Synthesis: given specification ϕ , find system S, such that $S \models \phi$
- Learning: given set of examples E, find system S, such that S is consistent with E and "generalizes well" ...
- Synthesis from spec + examples: given set of examples E and specification ϕ , find system S, such that S is consistent with E and $S \models \phi$
 - Key advantage: ϕ guides the generalization!

Conclusions

- We live in the world of software (and models of other systems, which are also software)
- Software is complex => difficult to get right
- Strong predictions about software require a hard science => formal methods, verification, synthesis
- Al/learning brings new challenges and opportunities

Thank you

• Questions?